

# CS443: Compiler Construction

Lecture 9: Structs

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Based on material from Stephen Chong, Steve Zdancewic and Greg Morrisett

# 2D (3D, etc.) Arrays

- By convention: “row major” order

```
int a[3][5]
```

[0][0]	[0][1]	[0][2]	[0][3]	[0][4]
[1][0]	[1][1]	[1][2]	[1][3]	[1][4]
[2][0]	[2][1]	[2][2]	[2][3]	[2][4]

# 2D (3D, etc.) Arrays

- By convention: “row major” order

```
int a[3][5]
```

[0][0]	[0][1]	[0][2]	[0][3]	[0][4]	[1][0]	[1][1]	[1][2]	[1][3]	[1][4]	[2][0]	[2][1]	[2][2]	[2][3]	[2][4]
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$$\text{Addr of } a[y][x] = 5 * y + x$$

# Structs in C and LLVM IR

```
struct person
{
    char name[];
    int age;
};

{ i8*, i32 }
```

# Recursive structs in C and LLVM IR

```
struct node
{
    int hd;
    node *tl;
};
```

```
%Tnode = type { i32, %Tnode* }
(Can name non-recursive structs too)
```

# getelementptr (general)

```
%elptr = getelementptr <ty>, <ty>* %ptr, <intty1> <val1>, ..., <inttyN> <valN>
```

- $<\text{ty}>$  is a (possibly structured) type
- $\% \text{ptr}$  is a pointer to an array of  $<\text{ty}>$ s (might just have one element)
- $<\text{val1}>$  is the index into the array
- $<\text{val2}>$  is the index of a field in the structure (if  $<\text{ty}>$  is a structure)
- $<\text{val3}>$  is the index of the field in *that* structure (if the  $<\text{val2}>$ th element of  $<\text{ty}>$  is a structure)...

(For structs, indices must be *i32 constants*)

```
struct person { char name []; int age; };  
person classlist[] = person[10];  
classlist[4].age = 20;
```

```
%Tpersion = { i8*, i32 }
```

```
%p4age = getelementptr %Tperson, %Tperson* %classlist, i32 4, i32 1  
store i32 20, i32* %p4age
```

4<sup>th</sup> element      1<sup>st</sup> field  
(0-indexed)

# GEP Example

```
struct RT {  
    int A;  
    int B[10][20];  
    int C;  
}  
struct ST {  
    struct RT X;  
    int Y;  
    struct RT Z;  
}  
int *foo(struct ST *s) {  
    return &s[1].Z.B[5][13];  
}
```

1. %s is a pointer to an (array of) %ST structs, suppose the pointer value is ADDR
2. Compute the index of the 1<sup>st</sup> element by adding size\_ty(%ST).
3. Compute the index of the Z field by adding size\_ty(%RT) + size\_ty(i32) to skip past X and Y.
4. Compute the index of the B field by adding size\_ty(i32) to skip past A.
5. Index into the 2d array.

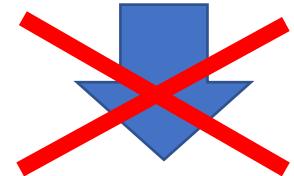
```
%RT = type { i32, [10 x [20 x i32]], i32 }  
%ST = type { %RT, i32, %RT }  
define i32* @foo(%ST* %s) {  
entry:  
    %arrayidx = getelementptr %ST* %s, i32 1, i32 2, i32 1, i32 5, i32 13  
    ret i32* %arrayidx  
}
```

Final answer: ADDR + size\_ty(%ST) + size\_ty(%RT) + size\_ty(i32)  
+ size\_ty(i32) + 5\*20\*size\_ty(i32) + 13\*size\_ty(i32)

Adapted from the LLVM reference by Stephen Chong, Harvard University

# Getelementptr does not access memory (ever!)

```
struct node { int hd; node *tl; };  
node tl1 = list.tl->tl;
```



```
%tl1 = getelementptr %Tnode, %Tnode* %list, i32 0, i32 1, i32 1
```

# Getelementptr does not access memory (ever!)

```
struct node { int hd; node *tl; };  
node tl1 = list.tl->tl;
```



```
%tlptr = getelementptr %Tnode, %Tnode* %list, i32 0, i32 1  
%tl = load %Tnode, %Tnode* %tlptr  
%tl1ptr = getelementptr %Tnode, %Tnode* %tl, i32 0, i32 1  
%tl1 = load %Tnode, %Tnode* %tl1ptr
```

# MiniC Syntax

t ::= void | bool | char | int | t[] | s | t((t id,)\*)

b ::= + | - | \* | / | && | || | > | >= | < | <= | != | ==

u ::= - | !

c ::= n | 'alpha'

lh ::= x | x[e] | x.f

e ::= c | x | e b e | u e | lh = e | new(t) | e((e, )\*) | e[e] | e.f | (t) e

s ::= t x [= e] | { (s;)\* } | e | if e s else s | for (s; e; e) s | break | continue  
| return [v]

d ::= (t x [= e])\* | t id ((t id, )\*) | struct id {(t id;)\*)}

# Arrays in MiniC

```
int a[] = new(int[20]);  
a[4] = 42;  
a[5] = a[4] + 1;
```

# Structs in MiniC

```
struct person
{
    char name [];
    int age;
};

int main () {
    char my_name [] = new(char[6]);
    my_name[0] = 's'; my_name[1] = 't'; ...;
    person stefan = new(person);
    stefan.name = my_name;
}
```

# You can pass structs and arrays around

```
void print_arr(char a[]) {  
    int i = 0;  
    while ((int)(a[i]) != 0) { printf("%c", a[i]); }  
    return;  
}
```

```
void print_name(person p) {  
    print_arr(p.name);  
}
```

# Arrays and structs are heap-allocated

→ `int a[] = new(int[4]);  
a[1] = 42;  
a[2] = a[1] + 1;`


Stack

0	
1	
2	
3	
4	
5	

Heap

# Arrays and structs are heap-allocated

→ `int a[] = new(int[4]);  
a[1] = 42;  
a[2] = a[1] + 1;`

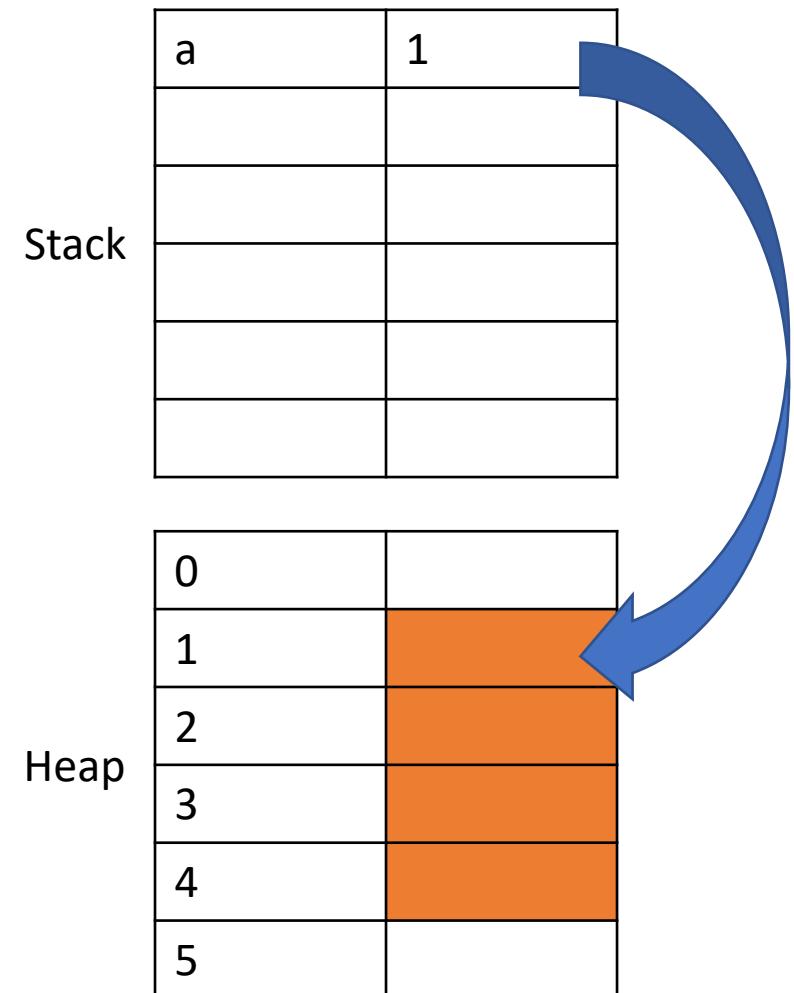

Stack

0	
1	
2	
3	
4	
5	

Heap

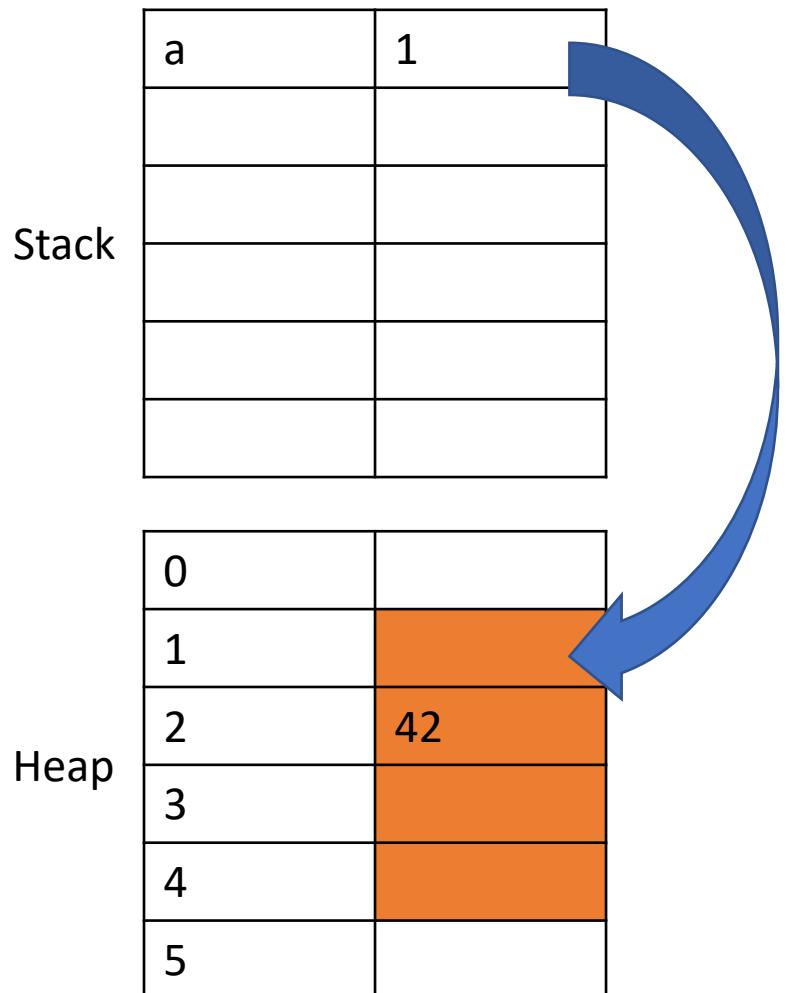
# Arrays and structs are heap-allocated

```
int a[] = new(int[4]);  
→ a[1] = 42;  
a[2] = a[1] + 1;
```



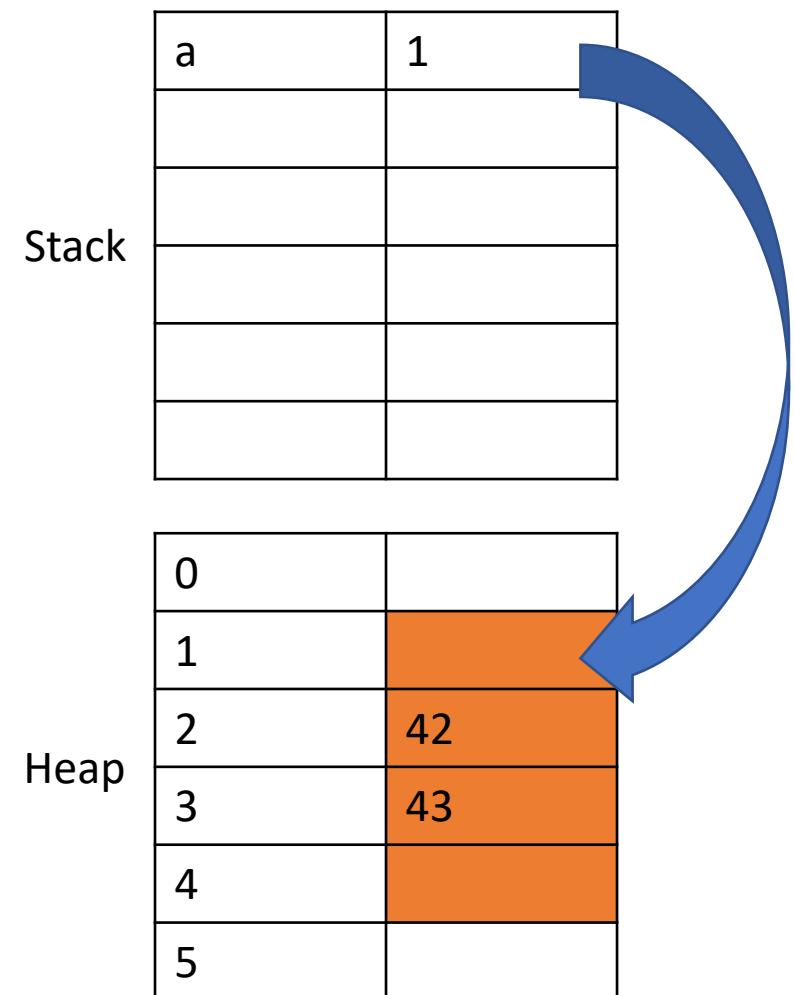
# Arrays and structs are heap-allocated

```
int a[] = new(int[4]);  
a[1] = 42;  
→ a[2] = a[1] + 1;
```



# Arrays and structs are heap-allocated

```
int a[] = new(int[4]);  
a[1] = 42;  
a[2] = a[1] + 1;
```



# Not stack allocated

```
int[] init_array() {  
    int a[] = new(int[4]);  
    a[1] = 42;  
    a[2] = a[1] + 1;  
    → return a;  
}
```

```
int main() {  
    int a[] = init_array();  
    foo();  
    return a[1];  
}
```

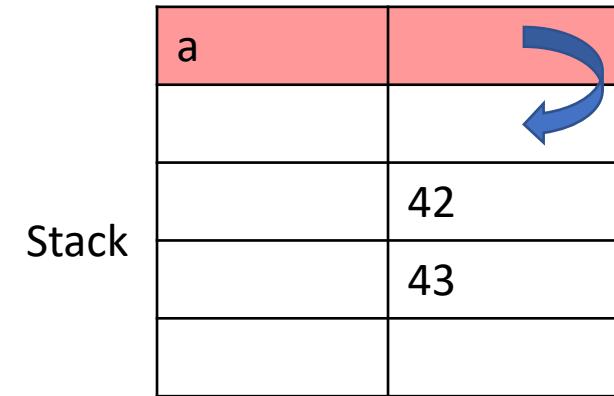
Stack

a	
a[0]	
a[1]	42
a[2]	43
a[3]	

# Not stack allocated

```
int[] init_array() {  
    int a[] = new(int[4]);  
    a[1] = 42;  
    a[2] = a[1] + 1;  
    return a;  
}
```

```
int main() {  
    int a[] = init_array();  
    → foo();  
    return a[1];  
}
```



# Not stack allocated

```
int[] init_array() {
    int a[] = new(int[4]);
    a[1] = 42;
    a[2] = a[1] + 1;
    return a;
}
```

```
int main() {
    int a[] = init_array();
    → foo();
    return a[1];
}
```

Stack

a	
baz	18
qux	34534
bar	93458
x	234

# Not stack allocated

```
int[] init_array() {  
    int a[] = new(int[4]);  
    a[1] = 42;  
    a[2] = a[1] + 1;  
    return a;  
}
```

```
int main() {  
    int a[] = init_array();  
    foo();  
    → return a[1];  
}
```

Stack

a	
	18
	34534
	93458
	234

# Compiling new

```
dest = new(t);
```

```
%dest = call i8* @malloc(i32 [size of t])
```

(Will also need to bitcast %dest to whatever t\* compiles to)